# CR Geometry and Analysis 

Howard Jacobowitz<br>Rutgers University - Camden

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& P=\{z, w):|z<1,|w|<1\}
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Theorem (Poincare (1905))
There does not exist a biholomorphism

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The identity component of the group of automorphism of $P$ leaving the origin fixed is given by

$$
(z, w) \rightarrow e^{i \theta_{1}} z, e^{i \theta_{2}} w
$$

and is commutative.

Two elements in the identity component of the group of automorphism of $B$ leaving the origin fixed are

$$
\begin{aligned}
\phi_{1} & =\left(\begin{array}{cc}
1 / \sqrt{2} & -1 / \sqrt{2} \\
1 / \sqrt{2} & 1 / \sqrt{2}
\end{array}\right) \\
\phi_{2} & =\left(\begin{array}{cc}
0 & e^{i \sigma} \\
-e^{-i \sigma} & 0
\end{array}\right) .
\end{aligned}
$$

For $0<\sigma<\pi, \phi_{1}$ and $\phi_{2}$ do not commute.

Theorem (Poincare)
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A real hypersurface is given locally by a graph

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y_{2}=f\left(x_{1}, x_{2}, y_{1}\right) .
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What are these invariants?

## Élie Cartan

I resolved this question with an application of my general method of equivalence. The complete solution of Poincaré's problem led me to new geometric ideas.

For the real hypersurface

$$
M=\{(z, w): \phi(z, w)=0\}
$$

the complex vector field

$$
L=\phi_{\bar{w}} \frac{\partial}{\partial \bar{z}}-\phi_{\bar{z}} \frac{\partial}{\partial \bar{w}}
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is tangent to $M$.

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Q=\left\{(z, w): \Im w=|z|^{2}\right\}
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with $z=x+i y$ and $w=u+i v(x, y, u)$

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We will see this operator again.

In general, given a choice of $L$, choose a real-valued form $\omega$ and a complex-valued form $\omega_{1}$

$$
\omega(L)=0, \quad \omega_{1}(L)=0, \quad \omega \wedge \omega_{1} \wedge \bar{\omega}_{1} \neq 0
$$

Normalize by $d \omega=i \omega_{1} \wedge \overline{\omega_{1}} \bmod \omega$.

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\Omega=|\lambda|^{2} \omega \text { and } \Omega_{1}=\lambda\left(\omega_{1}+\mu \omega\right)
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These are well-defined forms on a bundle of fiber dimension 4 over $M^{3}$.

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These are well-defined forms on a bundle of fiber dimension 4 over $M^{3}$. Set

$$
\Omega_{2}=\frac{d \lambda}{\lambda}+A \omega_{1}+B \bar{\omega}_{1}+C \omega
$$

and

$$
\Omega_{3}=\frac{1}{\bar{\lambda}}\left(d \mu+D \omega_{1}+E \overline{\omega_{1}}+F \omega\right) .
$$

Choose the coefficients to obtain

$$
d \Omega=i \Omega_{1} \wedge \bar{\Omega}_{1}+\left(\Omega_{2}+\overline{\Omega_{2}}\right) \wedge \Omega
$$

and

$$
d \Omega_{1}=\Omega_{2} \wedge \Omega_{1}+\Omega_{3} \wedge \Omega
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Only

$$
\rho=\Re C
$$

remains undetermined. Set

$$
\Omega_{4}=\frac{1}{|\lambda|^{2}}\{d \rho+\ldots\}
$$

to obtain

$$
\begin{aligned}
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d \Omega_{1} & =\Omega_{2} \wedge \Omega_{1}+\Omega_{3} \wedge \Omega \\
d \Omega_{2} & =2 i \Omega_{1} \wedge \bar{\Omega}_{3}+i \bar{\Omega}_{1} \wedge \Omega_{3}-\Omega \wedge \Omega_{4} \\
d \Omega_{3} & =-\Omega_{1} \wedge \Omega_{4}-\overline{\Omega_{2}} \wedge \Omega_{3}-R \Omega \wedge \overline{\Omega_{1}} \\
d \Omega_{4} & =i \Omega_{3} \wedge \overline{\Omega_{3}}-\left(\Omega_{2}+\overline{\Omega_{2}}\right) \wedge \Omega_{4}-S \Omega \wedge \Omega_{1}-\bar{S} \Omega \wedge \overline{\Omega_{1}}
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$R$ and $S$ are relative invariants.

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$R$ and $S$ are relative invariants. $R=0$ on some open set implies that $S=0$ on that open set and that there is a biholomorphism taking a possibly smaller open set of $M^{3}$ to the hyperquadric $Q$.
$R$ is called the curvature of the CR structure. It is an invariant of order 6 , not 9 .

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Now for some analysis.

Uniformly the experience of the investigated type has shown that speaking of existence in the local sense - there always were solutions, indeed smooth solutions, provided the equations were smooth enough. It was therefore a matter of considerable surprise to this author, to discover that this inference is in general erroneous. More precisely, there exist linear partial differential equations with coefficients in $\mathcal{C}^{\infty}$ which possess not a single smooth solution in any neighborhood.

Hans Lewy, An example of a smooth linear partial differential equation without solution, Annals of Mathematics 66 (1957).

Let $\phi\left(y_{1}\right)$ be a real-valued $C^{1}$ function.
Theorem
If there exists a $C^{1}$ solution to

$$
\left(-\left(\partial / \partial x_{1}\right)-i\left(\partial / \partial x_{2}\right)+2 i\left(x_{1}+i x_{2}\right)\left(\partial / \partial y_{1}\right)\right) u=2 \phi\left(y_{1}\right)
$$

in a neighborhood of a point $\left(0,0, y^{*}\right)$, then $\phi$ is analytic in some neighborhood of that point.

Set

$$
\partial_{\bar{z}}=\frac{1}{2}\left(\partial_{x}+i \partial_{y}\right)
$$

and write

$$
L u=-u_{\bar{z}}+i z u_{y_{1}}
$$

Theorem
If $L u=\phi\left(y_{1}\right)$ has a $C^{1}$ solution then $\phi$ is real analytic.
Let $w=y_{1}+i y_{2}$. For $y_{2}=|z|^{2}$, set

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U(w, \bar{w})=\int_{y_{2}=\text { constant }} u d z
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This is natural if we consider $u\left(x_{1}, x_{2}, y_{1}\right)$ as a function on $Q=\left\{w=y_{1}+i|z|^{2}\right\}$. Note that $U\left(y_{1}, 0\right)=0$.
Write $z=r e^{i \theta}$. So, $y_{2}=r^{2}$ and

$$
U(w, \bar{w})=\int_{0}^{2 \pi} i r e^{i \theta} u\left(r, \theta, y_{1}\right) d \theta
$$

## Claim

$$
\frac{\partial U}{\partial \bar{w}}=\frac{1}{2} \int L u d \theta .
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Assume the Claim.

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$V=U-2 \pi \psi$ is a holomorphic function of $w$ in some set

$$
\left\{a<y_{1}<b, 0<y_{2}<c\right\}
$$

and real on the real axis. The Reflection Principle applies and $V$ is holomorphic near the $y_{1}$ axis. Thus $\psi$ and $\phi$ are also real analytic as functions of $y_{1}$. So $L u=f$ is not always locally solvable.

The proof of the Claim is an integration by parts.

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\int_{0}^{2 \pi} u e^{i \theta} d \theta=i \int_{0}^{2 \pi} u_{\theta} e^{i \theta} d \theta
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\begin{aligned}
2 U_{\bar{w}} & =U_{y_{1}}+i U_{y_{2}} \\
& =\int u_{y_{1}} d z+i\left(i \int u_{\bar{z}} d \theta\right) \\
& =\int u_{y_{1}} i z d \theta-\int u_{\bar{z}} d \theta \\
& =\int L u d \theta
\end{aligned}
$$

A similar result holds for any strictly pseudo-convex hypersurface in $\mathbb{C}^{2}$ : The associated linear partial derivative operator is not always solvable.

## Abstract CR manifolds

$(\mathrm{H}, \mathrm{J})$ is an abstract CR structure on $\mathrm{M}^{3}$

- $H \subset T M$ is a two-plane distribution
- J is an anti-involution on H

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For $M^{3} \subset \mathbb{C}^{2}$ and $J_{0}: \mathbb{C}^{2} \rightarrow \mathbb{C}^{2}$

$$
H_{p}=T_{p}(M) \cap J_{0} T_{p}(M)=\text { the complex line tangent to } M \text { at } p
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A complex vector field $L$ on $M^{3}$ is an abstract CR structure if $\Re L$ and $\Im L$ are everywhere independent. Then

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H=\{\Re L, \Im L\} .
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J L=-i L .
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Cartan's construction also applies to abstract CR manifolds.

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Does every homogeneous linear partial differential equation have a non-trivial solution?

## Theorem (Nirenberg 1972)

There exists a smooth $C R$ operator such that $L h=0$ in a neighborhood of some given point $p$ implies that $d h(p)=0$. In fact, $h$ is a constant near $p$.

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(1) A two-dimensional Riemannian manifold is locally embeddable into $\mathbb{R}^{3}$ near every point of non-zero curvature (Weingarten 1884).
(2) There is an example of non-embeddability at a point of zero curvature (Pogorelov 1971).

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Nirenberg's example is a perturbation of the CR operator for the hyperquadric $Q$. So Nirenberg's example has curvature equal to zero at the origin.
(1) A two-dimensional Riemannian manifold is locally embeddable into $\mathbb{R}^{3}$ near every point of non-zero curvature (Weingarten 1884).
(2) There is an example of non-embeddability at a point of zero curvature (Pogorelov 1971).
(3) M is locally embeddable near $p$ if $K(p)=0, \nabla K \neq O(\operatorname{Lin} 1986)$.

## Theorem (Jacobowitz and Treves, 1982, 1983)

Let $L$ be the $C R$ operator of any strictly pseudo-convex $M^{3} \subset \mathbb{C}^{2}$ and let $p \in M^{3}$. There exists a complex vector field $\tilde{L}$ agreeing with $L$ to infinite order at $p$ such that $\tilde{L} h=0$ in a neighborhood of $p$ implies that $d h(p)=0$. In fact, $h$ is a constant near $p$.

Proof

For $M=\{\phi(z, w)=0\}, L=\phi_{\bar{w}} \partial_{\bar{z}}-\phi_{\bar{z}} \partial_{\bar{w}}$.

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A local biholomorphic change of coordinates yields $M=\{v=\rho(z, \bar{z}, u)\}$ with $\rho(0)=0, d \rho(0)=0$ and

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Set $\tilde{L}=L+f \partial_{z}+g \partial_{u}$. We want to choose $f$, vanishing to infinite order at 0 , such that $\tilde{L} h=0$ implies $h_{z}(0)=0$ and $g$ such that $h_{u}(0)=0$.

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Assume that for any neighborhood N of $0 \in \mathbb{R}^{3}$ there exist open sets $U \subset \Omega \subset N$, such that if $L h=\phi$ in $\Omega$ and $\operatorname{supp}(\phi) \subset U$, then

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If also $f>0$ in $U$ then $\Re h_{z}$ and $\Im h_{z}$ have zeroes in $U$. Next choose $N_{j} \rightarrow\{0\}$. Therefore $\Omega_{j}$ and $U_{j} \rightarrow\{0\}$ and so $h_{z}(0)=0$.

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There exists a curve $\gamma$ in the $\lambda$-plane such that

- Below $\gamma, \Gamma_{\lambda}$ is empty.
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Let $S=$ a torus foliated by curves $\Gamma_{\lambda}$ and $T$ the solid torus.

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If $L h=0$ in $\Omega-T$, then

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\int_{\Gamma_{\lambda}} h d z=0
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for $\Gamma_{\lambda} \subset \Omega-T$.

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## Proof.

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We want to show that

$$
\iiint_{T} L h d x d y d u=0
$$

if $\operatorname{supp}(L h) \subset T$.

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Thus

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\begin{aligned}
-\iiint_{T}(L h) d z d \bar{z} d u & =\iiint_{T} d(h d z d w) \\
& =\iint_{S} h d z d w \\
& =\iint_{\Gamma_{\lambda}} h d z d \lambda \\
& =0
\end{aligned}
$$

Thus, if $\operatorname{Supp}(f) \subset T_{j}$ and $f>0$ in each $T_{j}$, then from

$$
\left(L+f \partial_{z}\right) h=0
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in a neighborhood of the origin we have that $h_{z}(0)=0$.

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$$

in a neighborhood of the origin we have that $h_{z}(0)=0$. Using more open sets, an appropriate $g$, and a Baire category argument, we have

$$
\left(L+f \partial_{z}+g \partial_{u}\right) h=0
$$

in a neighborhood of the origin implies $h$ is a constant.

A CR embedding $f_{0}:\left(M^{3}, V_{0}\right) \rightarrow \mathbb{C}^{N}$ is stable if

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\left\|V_{1}-V_{0}\right\| \text { small } \Rightarrow \exists f_{1}:\left(M^{3}, V_{1}\right) \rightarrow \mathbb{C}^{N} \text { with }\left\|f_{1}-f_{0}\right\| \text { small. }
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No CR embedding is stable.

## Theorem (Lempert 1994)

Let $M^{3}$ be compact and $\left(M^{3}, V_{0}\right)$ be strictly pseudo-convex. Let $f_{0}:\left(M^{3}, V_{0}\right) \rightarrow \mathbb{C}^{2}$ be a CR embedding. If $\left(M^{3}, V_{1}\right)$ has a $C R$ embedding into some $\mathbb{C}^{N}$ then it has an embedding into $\mathbb{C}^{2}$ close to $f_{0}$.

# Theorem (Caitlin, Lempert, 1992) 

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There exists a strictly pseudo-convex compact $C R$ manifold in $\mathbb{C}^{3}$ that is not stable.

Why this difference between $\mathbb{C}^{2}$ and $\mathbb{C}^{3}$ ? Reasonable from a geometric point of view. $\left(M^{3}, V_{1}\right)$ has a CR embedding into some $\mathbb{C}^{N}$ is equivalent to $\bar{\partial}_{b}$ has closed range on functions. What other condition is necessary to distinguish between $\mathbb{C}^{2}$ and $\mathbb{C}^{3}$ ?

Theorem (most likely) (Siqi Fu, Weixia Zhu)

- Let $\left(M^{3}, V_{t}\right)$ be a smooth family of compact pseudo-convex CR manifolds of finite type. The existence of a uniform closed range estimate for $\bar{\partial}_{b}^{t}$ implies stability of the family.
- Let $\left(M^{3}, V_{t}\right)$ be a smooth family of compact pseudo-convex CR manifolds of finite type. If the Kohn Laplacian $\square_{b}^{t}$ acting on functions has a uniform spectral gap, then the family is stable.

Conjecture
Lempert's result holds for strictly pseudo-convex replaced by pseudoconvex of finite type.

## THANK YOU

