# CR Geometry and Analysis

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## Theorem (Poincare (1905))

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The identity component of the group of automorphism of P leaving the origin fixed is given by

$$(z, w) \rightarrow e^{i\theta_1}z, e^{i\theta_2}w.$$

and is commutative.

Two elements in the identity component of the group of automorphism of B leaving the origin fixed are

$$\phi_1 = \begin{pmatrix} 1/\sqrt{2} & -1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix}$$
$$\phi_2 = \begin{pmatrix} 0 & e^{i\sigma} \\ -e^{-i\sigma} & 0 \end{pmatrix}.$$

For  $0 < \sigma < \pi$ ,  $\phi_1$  and  $\phi_2$  do not commute.

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What are these invariants?

#### Élie Cartan

I resolved this question with an application of my general method of equivalence. The complete solution of Poincaré's problem led me to new geometric ideas.

For the real hypersurface

$$M = \{(z, w) : \phi(z, w) = 0\}$$

the complex vector field

$$L = \phi_{\bar{w}} \frac{\partial}{\partial \bar{z}} - \phi_{\bar{z}} \frac{\partial}{\partial \bar{w}}$$

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$$Q = \{(z, w) : \Im w = |z|^2\}$$

with z = x + iy and w = u + iv(x, y, u)

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We will see this operator again.

In general, given a choice of L, choose a real-valued form  $\omega$  and a complex-valued form  $\omega_1$ 

$$\omega(L) = 0, \quad \omega_1(L) = 0, \quad \omega \wedge \omega_1 \wedge \overline{\omega_1} \neq 0.$$

Normalize by  $d\omega=i\omega_1\wedge \bar{\omega_1}\mod \omega$  .

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$$\Omega = |\lambda|^2 \omega$$
 and  $\Omega_1 = \lambda(\omega_1 + \mu\omega)$ 

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$$\Omega_2 = \frac{d\lambda}{\lambda} + A\omega_1 + B\bar{\omega_1} + C\omega$$

and

$$\Omega_3 = rac{1}{ar{\lambda}}(d\mu + D\omega_1 + Ear{\omega_1} + F\omega).$$

Choose the coefficients to obtain

$$d\Omega = i\Omega_1 \wedge \bar{\Omega_1} + (\Omega_2 + \bar{\Omega_2}) \wedge \Omega$$

and

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Only

$$\rho = \Re C$$

remains undetermined. Set

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R and S are relative invariants.

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R and S are relative invariants. R=0 on some open set implies that S=0 on that open set and that there is a biholomorphism taking a possibly smaller open set of  $M^3$  to the hyperquadric Q.

R is called the curvature of the CR structure. It is an invariant of order 6, not 9.

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Now for some analysis.

Uniformly the experience of the investigated type has shown that - speaking of existence in the local sense - there always were solutions, indeed smooth solutions, provided the equations were smooth enough. It was therefore a matter of considerable surprise to this author, to discover that this inference is in general erroneous. More precisely, there exist linear partial differential equations with coefficients in  $\mathcal{C}^\infty$  which possess not a single smooth solution in any neighborhood.

Hans Lewy, An example of a smooth linear partial differential equation without solution, Annals of Mathematics 66 (1957).

Let  $\phi(y_1)$  be a real-valued  $C^1$  function.

#### **Theorem**

If there exists a  $C^1$  solution to

$$(-(\partial/\partial x_1) - i(\partial/\partial x_2) + 2i(x_1 + ix_2)(\partial/\partial y_1))u = 2\phi(y_1)$$

in a neighborhood of a point  $(0,0,y^*)$ , then  $\phi$  is analytic in some neighborhood of that point.

Set

$$\partial_{\bar{z}} = \frac{1}{2} (\partial_x + i \partial_y)$$

and write

$$Lu = -u_{\bar{z}} + izu_{y_1}$$

#### **Theorem**

If  $Lu = \phi(y_1)$  has a  $C^1$  solution then  $\phi$  is real analytic.

Let  $w = y_1 + iy_2$ . For  $y_2 = |z|^2$ , set

$$U(w, \bar{w}) = \int_{y_2 = constant} u dz.$$

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This is natural if we consider  $u(x_1, x_2, y_1)$  as a function on  $Q = \{w = y_1 + i|z|^2\}$ . Note that  $U(y_1, 0) = 0$ . Write  $z = re^{i\theta}$ . So,  $y_2 = r^2$  and

$$U(w, \bar{w}) = \int_0^{2\pi} ire^{i\theta} u(r, \theta, y_1) d\theta.$$

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Assume the Claim.

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 $V=U-2\pi\psi$  is a holomorphic function of w in some set

$${a < y_1 < b, 0 < y_2 < c}$$

and real on the real axis. The Reflection Principle applies and V is holomorphic near the  $y_1$  axis. Thus  $\psi$  and  $\phi$  are also real analytic as functions of  $y_1$ . So Lu=f is not always locally solvable.

$$\int_0^{2\pi} u e^{i\theta} d\theta = i \int_0^{2\pi} u_\theta e^{i\theta} d\theta.$$

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  $z = r e^{i\theta}$  and  $2\partial_{\bar{z}} = e^{i\theta} (\partial_r + \frac{1}{r} \partial_{\theta})$   $y_2 = r^2$  and  $\partial_{y_2} = \frac{1}{2r} \partial_r$ 

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$$2U_{\bar{w}} = U_{y_1} + iU_{y_2}$$

$$= \int u_{y_1} dz + i(i \int u_{\bar{z}} d\theta)$$

$$= \int u_{y_1} iz d\theta - \int u_{\bar{z}} d\theta$$

$$= \int Lu d\theta.$$

A similar result holds for any strictly pseudo-convex hypersurface in  $\mathbb{C}^2$ : The associated linear partial derivative operator is not always solvable.

(H,J) is an <u>abstract CR structure on M<sup>3</sup></u>

- $H \subset TM$  is a two-plane distribution
- J is an anti-involution on H

$$J: H \to H, \quad J^2 = -I$$

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For  $M^3\subset\mathbb{C}^2$  and  $J_0:\mathbb{C}^2 o\mathbb{C}^2$ 

 $H_p = T_p(M) \cap J_0T_p(M) =$  the complex line tangent to M at p

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$$J=J_0|_H$$
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$$H = \{\Re L, \Im L\}.$$

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Cartan's construction also applies to abstract CR manifolds.

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Does every homogeneous linear partial differential equation have a non-trivial solution?

## Theorem (Nirenberg 1972)

There exists a smooth CR operator such that Lh=0 in a neighborhood of some given point p implies that dh(p)=0. In fact, h is a constant near p.

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 $\bullet$  A two -dimensional Riemannian manifold is locally embeddable into  $\mathbb{R}^3$  near every point of non-zero curvature (Weingarten 1884).

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- There is an example of non-embeddability at a point of zero curvature (Pogorelov 1971).
- **3** M is locally embeddable near p if K(p) = 0,  $\nabla K \neq O$  (Lin 1986).

## Theorem (Jacobowitz and Treves, 1982, 1983)

Let L be the CR operator of any strictly pseudo-convex  $M^3 \subset \mathbb{C}^2$  and let  $p \in M^3$ . There exists a complex vector field  $\tilde{L}$  agreeing with L to infinite order at p such that  $\tilde{L}h = 0$  in a neighborhood of p implies that dh(p) = 0. In fact, h is a constant near p.

For 
$$M = \{\phi(z, w) = 0\}$$
,  $L = \phi_{\bar{w}}\partial_{\bar{z}} - \phi_{\bar{z}}\partial_{\bar{w}}$ .

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,  $L=\phi_{\bar{w}}\partial_{\bar{z}}-\phi_{\bar{z}}\partial_{\bar{w}}$ . A local biholomorphic change of coordinates yields  $M=\{v=\rho(z,\bar{z},u)\}$  with  $\rho(0)=0,d\rho(0)=0$  and

$$L = (1 + i\rho_u)\partial_{\bar{z}} - i\rho_{\bar{z}}\partial_u$$

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Set  $\tilde{L} = L + f\partial_z + g\partial_u$ . We want to choose f, vanishing to infinite order at 0, such that  $\tilde{L}h = 0$  implies  $h_z(0) = 0$  and g such that  $h_u(0) = 0$ .

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$$\iiint_U \phi dx dy du = 0.$$

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Write  $\tilde{L}h=0$  as  $Lh=-fh_z$  and take g=0. If  $supp(f)\subset U$  then

$$\iiint_{U} fh_z dx dy dz = 0.$$

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If also f>0 in U then  $\Re h_z$  and  $\Im h_z$  have zeroes in U. Next choose  $N_j\to\{0\}$ . Therefore  $\Omega_j$  and  $U_j\to\{0\}$  and so  $h_z(0)=0$ .

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There exists a curve  $\gamma$  in the  $\lambda$ -plane such that

- Below  $\gamma$ ,  $\Gamma_{\lambda}$  is empty.
- On  $\gamma$ ,  $\Gamma_{\lambda}$  is a point .
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Let S = a torus foliated by curves  $\Gamma_{\lambda}$  and T the solid torus.

#### Lemma

If 
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 in  $\Omega - T$ , then

$$\int_{\Gamma_{\lambda}} h dz = 0$$

for 
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We want to show that

$$\iiint_T Lhdxdydu = 0$$

if  $supp(Lh) \subset T$ .

Since Lz=0 and Lw=0, it follows that  $d \big( h dz dw \big) = -L u dz d \bar{z} du.$ 

Since Lz = 0 and Lw = 0, it follows that

$$d(hdzdw) = -Ludzd\bar{z}du.$$

Thus

$$-\iiint_{T} (Lh)dzd\bar{z}du = \iiint_{T} d(hdzdw)$$

$$= \iint_{S} hdzdw$$

$$= \iint_{\Gamma_{\lambda}} hdzd\lambda$$

$$= 0.$$

Thus, if  $Supp(f) \subset T_j$  and f > 0 in each  $T_j$ , then from

$$(L+f\partial_z)h=0$$

in a neighborhood of the origin we have that  $h_z(0) = 0$ .

Thus, if  $Supp(f) \subset T_j$  and f > 0 in each  $T_j$ , then from

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in a neighborhood of the origin we have that  $h_z(0)=0$ . Using more open sets, an appropriate g, and a Baire category argument, we have

$$(L+f\partial_z+g\partial_u)h=0$$

in a neighborhood of the origin implies h is a constant.

A CR embedding  $f_0:(M^3,V_0)\to\mathbb{C}^N$  is stable if

 $||V_1 - V_0||$  small  $\Rightarrow \exists f_1 : (M^3, V_1) \rightarrow \mathbb{C}^N$  with  $||f_1 - f_0||$  small.

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No CR embedding is stable.

## Theorem (Lempert 1994)

Let  $M^3$  be compact and  $(M^3, V_0)$  be strictly pseudo-convex. Let  $f_0: (M^3, V_0) \to \mathbb{C}^2$  be a CR embedding. If  $(M^3, V_1)$  has a CR embedding into some  $\mathbb{C}^N$  then it has an embedding into  $\mathbb{C}^2$  close to  $f_0$ .

There exists a strictly pseudo-convex compact CR manifold in  $\mathbb{C}^3$  that is not stable.

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 $(M^3, V_1)$  has a CR embedding into some  $\mathbb{C}^N$  is equivalent to  $\bar{\partial}_b$  has closed range on functions. What other condition is necessary to distinguish between  $\mathbb{C}^2$  and  $\mathbb{C}^3$ ?

#### Theorem (most likely) (Siqi Fu, Weixia Zhu)

- Let  $(M^3, V_t)$  be a smooth family of compact pseudo-convex CR manifolds of finite type. The existence of a uniform closed range estimate for  $\bar{\partial}_b^t$  implies stability of the family.
- Let  $(M^3, V_t)$  be a smooth family of compact pseudo-convex CR manifolds of finite type. If the Kohn Laplacian  $\Box_b^t$  acting on functions has a uniform spectral gap, then the family is stable.

#### Conjecture

Lempert's result holds for strictly pseudo-convex replaced by pseudoconvex of finite type.

#### THANK YOU